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A Appendix

A.1 Convex Relaxation and Dual of Problem (11)

Since problem (11) is a mixed integer problem regarding η and μ , it is hard to directly optimize. Motivated by (Tan *et al.* 2010), we apply convex relaxation and Lagrange dual to make some transformations.

Firstly, we introduce dual variables $\alpha, \beta \in \mathbb{R}^{N_h}$ for the hingle loss constraint:

$$\ell(\boldsymbol{\mu}, \boldsymbol{\eta}; (\mathbf{x}_i, y_i)) = \max(0, 1 - y_i \boldsymbol{\mu}^T(\boldsymbol{\eta} \odot \mathbf{x}_i)).$$
(21)

As to problem (11), we can get the Lagrangian function of the inner problem w.r.t μ :

$$\mathcal{L}(\boldsymbol{\mu}, \ell, \boldsymbol{\alpha}, \boldsymbol{\beta}) = \frac{1}{2} (\boldsymbol{\mu} - \boldsymbol{\mu}_{h-1})^T \boldsymbol{\Sigma}_h(\boldsymbol{\eta})^{-1} (\boldsymbol{\mu} - \boldsymbol{\mu}_{h-1}) + \frac{C}{q} \sum_{i=1}^{N_h} D_i \ell(\boldsymbol{\mu}, \boldsymbol{\eta}; (\mathbf{x}_i, y_i))^q + \sum_{i=1}^{N_h} (-\beta_i \ell(\boldsymbol{\mu}, \boldsymbol{\eta}; (\mathbf{x}_i, y_i))) + \sum_{i=1}^{N_h} \alpha_i (1 - y_i (\boldsymbol{\mu} \odot \boldsymbol{\eta})^T \mathbf{x}_i - \ell(\boldsymbol{\mu}, \boldsymbol{\eta}; (\mathbf{x}_i, y_i)))$$
(22)

By taking derivative over variables μ and ℓ , we get:

$$\nabla_{\boldsymbol{\mu}} \mathcal{L} = \boldsymbol{\Sigma}(\boldsymbol{\eta})^{-1} (\boldsymbol{\mu} - \boldsymbol{\mu}_{h-1}) - \sum_{i=1}^{N_h} \alpha_i y_i (\mathbf{x}_i \odot \boldsymbol{\eta}) = 0$$

$$\nabla_{\ell_i} \mathcal{L} = CD_i - \alpha_i - \beta_i = 0, \alpha_i, \beta_i \ge 0, \text{ for } \mathbf{q} = 1,$$

$$\nabla_{\ell_i} \mathcal{L} = CD_i \ell_i - \alpha_i - \beta_i = 0, \beta_i = 0, \text{ for } \mathbf{q} = 2.$$

With some transformations, then:

$$\boldsymbol{\mu} - \boldsymbol{\mu}_{h-1} = \boldsymbol{\Sigma}(\boldsymbol{\eta}) \sum_{i=1}^{N_h} \alpha_i y_i(\mathbf{x}_i \odot \boldsymbol{\eta}),$$

$$0 \le \alpha_i \le CD_i, \text{ for } \mathbf{q} = 1,$$

$$\ell_i = \alpha_i / (CD_i), \text{ for } \mathbf{q} = 2.$$

Let $\mathbf{g}(\boldsymbol{\alpha}, \boldsymbol{\eta}) := \sum_{i=1}^{N_h} \alpha_i y_i(\mathbf{x}_i \odot \boldsymbol{\eta}), \ \mathcal{A} := \{ \boldsymbol{\alpha} \in \mathbb{R}^{N_h} | 0 \le \alpha_i \le U, \forall i \in [N_h] \}$ is the domain of $\boldsymbol{\alpha}$ (here, U =

 CD_i for q = 1 and $U = \infty$ for q = 2), then we can get the dual of inner problem (11) as:

$$\max_{\boldsymbol{\alpha}\in\boldsymbol{\Lambda}} -\frac{1}{2}\mathbf{g}(\boldsymbol{\alpha},\boldsymbol{\eta})^{T}\boldsymbol{\Sigma}(\boldsymbol{\eta})\mathbf{g}(\boldsymbol{\alpha},\boldsymbol{\eta}) - \frac{q-1}{2C}\sum_{i=1}^{N_{h}}\frac{\alpha_{i}^{2}}{D_{i}} + \sum_{i=1}^{N_{h}}\alpha_{i} - \boldsymbol{\mu}_{h-1}^{T}\mathbf{g}(\boldsymbol{\alpha},\boldsymbol{\eta}),$$
(23)

We define objective of (23) as $f(\alpha, \eta)$ for convenience. Problem (11) can be reformulated as a minmax problem:

$$\min_{\boldsymbol{\eta} \in \boldsymbol{\Lambda}} \max_{\boldsymbol{\alpha} \in \mathcal{A}} f(\boldsymbol{\alpha}, \boldsymbol{\eta}), \tag{24}$$

This problem is also a mixed integer problem, but we have the following property according to minmax inequality (Sion 1958):

$$\min_{\boldsymbol{\eta} \in \boldsymbol{\Lambda}} \max_{\boldsymbol{\alpha} \in \mathcal{A}} f(\boldsymbol{\alpha}, \boldsymbol{\eta}) \ge \max_{\boldsymbol{\alpha} \in \mathcal{A}} \min_{\boldsymbol{\eta} \in \boldsymbol{\Lambda}} f(\boldsymbol{\alpha}, \boldsymbol{\eta}), \quad (25)$$

The latter problem of (25) provides a lower bound to problem (24) and it is also a convex problem. By introducing a variable θ , we can transform the problem into :

$$\max_{\theta \in \mathbb{R}, \alpha \in \mathcal{A}} \theta, \text{ s.t. } \theta \le f(\alpha, \eta), \forall \eta \in \Lambda.$$
 (26)

A.2 Solving for the Primal of Problem (15)

We prove that problem (16) is the primal of problem (15).

Let $\Omega(\mathbf{w}) = \frac{1}{2} (\sum_{k=1}^{K} \|\mathbf{w}_k - \mathbf{w}_k^{h-1}\|)^2$. Define second order crone $Q_r = \{(\mathbf{u}, \mathbf{v}) \in \mathbb{R}^{r+1}, \|\mathbf{u}\|_2 \leq v\}$. Let $\mathbf{z}_k = \|\mathbf{w}_k - \mathbf{w}_k^{h-1}\|$, then $\Omega(\mathbf{w}) = \frac{1}{2}\mathbf{z}^2$, where $\mathbf{z} = \sum_{k=1}^{K} \mathbf{z}_k, \mathbf{z}_k \geq \mathbf{0}$ and $\mathbf{z} \geq \mathbf{0}$. Then problem (16) can be reformulated as:

$$\min_{\mathbf{z},\mathbf{w}_{k},\ell} \frac{1}{2} \mathbf{z}^{2} + \frac{C}{q} \sum_{i=1}^{N_{h}} D_{i} \ell(\mathbf{w}_{k}, \boldsymbol{\eta})^{q},$$
s.t.
$$\sum_{k=1}^{K} \mathbf{z}_{k} \leq \mathbf{z}, (\mathbf{w}_{k} - \mathbf{w}_{k}^{h-1}, \mathbf{z}_{k}) \in \mathcal{Q}_{r}, \quad (27)$$

We introduce $\alpha, \beta, \gamma, \delta, \epsilon$ here. With δ, ϵ and the constraints on second order crone Q_r , we point out that $\delta_k^T(\mathbf{w}_k -$

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 \mathbf{w}_{k}^{h-1}) + $\epsilon_{k}\mathbf{z}_{k}$ along with $\|\boldsymbol{\delta}_{k}\| \leq \epsilon_{k}$ equals original constraints on Q_{r} with Lagrangian multiplier. Now Lagrangian function can be written as:

$$\mathcal{L}(\mathbf{z}, \mathbf{w}_{k}, \ell, \boldsymbol{\alpha}, \boldsymbol{\beta}, \gamma, \boldsymbol{\delta}, \boldsymbol{\epsilon}) = \frac{1}{2}\mathbf{z}^{2} + \frac{C}{q}\sum_{i=1}^{N_{h}} D_{i}\ell_{i}^{q} + \sum_{i=1}^{N_{h}} (-\beta_{i}\ell_{i})$$
$$-\sum_{k=1}^{K} (\boldsymbol{\delta}_{k}^{T}(\mathbf{w}_{k} - \mathbf{w}_{k}^{h-1}) + \epsilon_{k}\mathbf{z}_{k}) + \gamma(\sum_{k=1}^{K} \mathbf{z}_{k} - \mathbf{z})$$
$$+\sum_{i=1}^{N_{h}} \alpha_{i}(1 - y_{i}\sum_{k=1}^{K} \mathbf{w}_{k}^{T}\widehat{\mathbf{x}}_{i}^{k} - \ell_{i}).$$
(28)

Taking derivatives w.r.t $\mathbf{z}, \mathbf{w}_k, \ell_i$, the KKT condition is as follows:

$$\begin{split} \nabla_{\mathbf{z}} \mathcal{L} &= \mathbf{z} - \gamma = 0, \\ \nabla_{\mathbf{z}_k} \mathcal{L} &= \gamma - \epsilon_k = 0, \\ \nabla_{\mathbf{w}_k} \mathcal{L} &= -\sum_{i=1}^{N_h} \alpha_i y_i \widehat{\mathbf{x}}_i^k - \boldsymbol{\delta}_k = 0, \\ \nabla_{\ell_i} \mathcal{L} &= CD_i - \alpha_i - \beta_i = 0, \alpha_i, \beta_i \ge 0, \text{ for } \mathbf{q} = 1, \\ \nabla_{\ell_i} \mathcal{L} &= CD_i \ell_i - \alpha_i - \beta_i = 0, \beta_i = 0, \text{ for } \mathbf{q} = 2, \\ \| \boldsymbol{\delta}_k \| \le \epsilon_k. \end{split}$$

Substituting all the equations back into Lagrangian function, we have

$$\mathcal{L}(\mathbf{z}, \mathbf{w}_k, \ell, \boldsymbol{\alpha}, \boldsymbol{\beta}, \gamma, \boldsymbol{\delta}, \boldsymbol{\epsilon}) = -\frac{1}{2}\gamma^2 - \frac{q-1}{2C}\sum_{i=1}^{N_h} \frac{\alpha_i^2}{D_i} + \sum_{i=1}^{N_h} \alpha_i + \sum_{k=1}^{K} \boldsymbol{\delta}^k \mathbf{w}_k^{h-1}.$$
(29)

Let $\mathcal{A} := \{ \boldsymbol{\alpha} \in \mathbb{R}^{N_h} | 0 \leq \alpha_i \leq U \}$ be the domain of $\boldsymbol{\alpha}$ where $U = CD_i$ for q = 1 and $U = \infty$ for q = 2. We then rewrite dual problem of Lagrangian:

$$\max_{\gamma \in \mathbb{R}, \boldsymbol{\alpha} \in \mathcal{A}} \mathcal{L}(\mathbf{z}, \mathbf{w}_k, \ell, \boldsymbol{\alpha}, \boldsymbol{\beta}, \gamma, \boldsymbol{\delta}, \boldsymbol{\epsilon})$$

s.t. $\|\sum_{k=1}^{K} \alpha_i y_i \widehat{\mathbf{x}}_i^k\| \le \gamma, k = 1, \dots, K$ (30)

Let $\theta := \mathcal{L}(\mathbf{z}, \mathbf{w}_k, \ell, \boldsymbol{\alpha}, \boldsymbol{\beta}, \gamma, \boldsymbol{\delta}, \boldsymbol{\epsilon})$ and $\mathbf{g}(\boldsymbol{\alpha}, \boldsymbol{\eta}_k) = \sum_{k=1}^{K} \alpha_i y_i(\widehat{\mathbf{x}}_i \odot \boldsymbol{\eta}_k)$. We further define $f(\boldsymbol{\alpha}, \boldsymbol{\eta}_k) = -\frac{1}{2} \mathbf{g}(\boldsymbol{\alpha}, \boldsymbol{\eta}_k)^T \mathbf{g}(\boldsymbol{\alpha}, \boldsymbol{\eta}_k) - \frac{q-1}{2C} \sum_{i=1}^{N_h} \frac{\alpha_i^2}{D_i} + \sum_{i=1}^{N_h} \alpha_i - (\mathbf{w}_k^{h-1})^T \mathbf{g}(\boldsymbol{\alpha}, \boldsymbol{\eta}_k)$. Then,

$$\max_{\theta, \alpha \in \mathcal{A}} \theta, \text{ s.t. } \theta \le f(\alpha, \eta_k), k = 1, \dots, K.$$
 (31)

Since $\hat{\mathbf{x}}_i = \boldsymbol{\Sigma}_k^{\frac{1}{2}} \mathbf{x}_i$, with some transformation, we can get that (31) is equivalent to (15).

A.3 Conjugate Dual of Problem (17)

Problem (17) can be written as:

$$\min_{\mathbf{w}} \Omega(\mathbf{w}) + C \sum_{i=1}^{N_h} L_i(\mathbf{w}^T \widehat{\mathbf{x}}_i).$$
(32)

Let $p_i := \mathbf{w}^T \widehat{\mathbf{x}}_i$, (32) can be reformulated as:

$$\min_{\mathbf{w}} \Omega(\mathbf{w}) + C \sum_{i=1}^{N_h} L_i(p_i), \text{ s.t. } p_i = \mathbf{w}^T \widehat{\mathbf{x}}_i, i = 1, \dots, N_h$$
(33)

Now the Lagrangian function:

$$\mathcal{L}(\mathbf{w}, \mathbf{p}, \boldsymbol{\alpha}) = \Omega(\mathbf{w}) + C \sum_{i=1}^{N_h} L_i(\mathbf{p}_i) + C \sum_{i=1}^{N_h} \alpha_i (p_i - \mathbf{w}^T \widehat{\mathbf{x}}_i)$$
$$= \Omega(\mathbf{w}) - C \sum_{i=1}^{N_h} \alpha_i \mathbf{w}^T \widehat{\mathbf{x}}_i + C \sum_{i=1}^{N_h} (L_i(p_i) + \alpha_i p_i).$$
(34)

Let $\mathbf{z}(\alpha) = C \sum_{i=1}^{N_h} \alpha_i \hat{\mathbf{x}}_i$. If we decouple w and p, and minimize Lagrangian function w.r.t w and p, then:

$$\min_{\mathbf{w},\mathbf{p}} \mathcal{L}(\mathbf{w},\mathbf{p},\boldsymbol{\alpha})
= \min_{\mathbf{w}} (\Omega(\mathbf{w}) - \mathbf{w}^T \mathbf{z}(\boldsymbol{\alpha})) + \min_{\mathbf{p}} C \sum_{i=1}^{N_h} (L_i(p_i) + \alpha_i p_i)
= -\max_{\mathbf{w}} (\mathbf{w}^T \mathbf{z}(\boldsymbol{\alpha}) - \Omega(\mathbf{w})) - \max_{\mathbf{p}} C \sum_{i=1}^{N_h} (-\alpha_i p_i - L_i(p_i))
= -\Omega^*(\mathbf{z}(\boldsymbol{\alpha})) - C \sum_{i=1}^{N_h} L_i^*(-\alpha_i).$$
(35)

Thus the dual problem is:

$$\max_{\boldsymbol{\alpha} \ge \boldsymbol{0}} -\Omega^*(\mathbf{z}(\boldsymbol{\alpha})) - C \sum_{i=1}^{N_h} L_i^*(-\alpha_i).$$
(36)

A.4 Computation of $\nabla^* \Omega(\mathbf{z}(\boldsymbol{\alpha}))$

In order to solve w, we need to compute $\mathbf{w} = \nabla^* \Omega(\mathbf{z})$ given \mathbf{z} and \mathbf{w}_{h-1} . Based on the conjugate dual property, we have the following problem:

$$\mathbf{w} = \arg \max_{\mathbf{w}} \mathbf{w}^{T} \mathbf{z} - \Omega(\mathbf{w})$$

$$= \arg \max_{\mathbf{w}} \mathbf{w}^{T} \mathbf{z} - \frac{\sigma}{2} \|\mathbf{w} - \mathbf{w}_{h-1}\|^{2} - \frac{1}{2} (\sum_{k=1}^{K} \|\mathbf{w}_{k} - \mathbf{w}_{k}^{h-1}\|^{2})$$

$$= \arg \max_{\mathbf{w}} - \frac{\sigma}{2} \|\mathbf{w} - \mathbf{w}_{h-1} - \frac{\mathbf{z}}{\sigma}\|^{2} - \frac{1}{2} (\sum_{k=1}^{K} \|\mathbf{w}_{k} - \mathbf{w}_{k}^{h-1}\|^{2})$$

$$= \arg \min_{\mathbf{w}} \frac{\sigma}{2} \|\mathbf{w} - \mathbf{w}_{h-1} - \frac{\mathbf{z}}{\sigma}\|^{2} + \frac{1}{2} (\sum_{k=1}^{K} \|\mathbf{w}_{k} - \mathbf{w}_{k}^{h-1}\|^{2})$$
(37)

Problem (37) is strictly convex problem, thus a unique minimizer exits, and can be computed in close-form. According to (Martins *et al.* 2011), we give the detailed solution as shown in Algorithm 3.

Algorithm 3 Computation of $\mathbf{w} = \nabla^* \Omega(\mathbf{z})$

Require: $\mathbf{z}, \mathbf{w}_{h-1}$, parameter $\frac{1}{\sigma}$. Initialize $\boldsymbol{\omega} = \frac{z}{\sigma}$. Compute $\hat{o}_k = \|\boldsymbol{\omega}_k\|$ where $\boldsymbol{\omega}_k$ is associated with \mathbf{w}_k for $k = 1, \dots, K$ Sort $\hat{\mathbf{o}}$ to obtain $\bar{\mathbf{o}}$ such that $\bar{o}_1 \geq \dots \geq \bar{o}_K$. Find $\rho = \max\{k | \bar{o}_k - \frac{s}{1+ks} \sum_{i=1}^k \bar{o}_i > 0, k = 1, \dots, K\}$. Compute a threshold value $\zeta = \frac{s}{1+\rho s} \sum_{i=1}^\rho \bar{o}_i$. Calculate \mathbf{o} , where $o_k = \begin{cases} \widehat{o}_k - \zeta, & \text{if } \widehat{o}_k > \zeta, \\ 0, & \text{Otherwise.} \end{cases}$. Calculate $\widehat{\boldsymbol{\omega}}_k = \begin{cases} \frac{o_k}{\|\boldsymbol{\omega}_k\|} \boldsymbol{\omega}_k, & \text{if } o_k > 0, \\ 0, & \text{Otherwise.} \end{cases}$. Let $\mathbf{w} = [\widehat{\boldsymbol{\omega}}_k]_{k=1}^K$ and return \mathbf{w} .

A.5 Online Update of Imbalance Measures

In this paper, we focus on three performance measures: Fmeasure, AUROC and AUPRC instead of mistake number or classification loss used in traditional methods. According to Algorithm 2, we need to maintain and update the performance measures M_{h+1}^j at each iteration h. However, if we directly compute M_{h+1}^j , it is computation expensive and requires to store all historical predictions and labels, which is really inefficient. Instead, we present how to update M_{h+1}^j by only using M_h and current $\mathbf{f_h}, \mathbf{y}_h$.

For F-measure, let $\bar{\mathbf{y}}_h = (\mathbf{y}_h + 1)/2$ and $\hat{\mathbf{y}}_h = \operatorname{sign}(\mathbf{f}_h > 0)$, $a_h = \sum_{\tau=1}^h \bar{\mathbf{y}}_\tau \cdot \hat{\mathbf{y}}_\tau$, $c_h = \sum_{\tau=1}^h \sum_{\tau=1}^h \bar{\mathbf{y}}_\tau + \sum_{\tau=1}^h \sum_{\tau=1}^h \hat{\mathbf{y}}_\tau$. We can calculate F-measure as: $F_{h+1} = \frac{2a_h}{c_h}$. In order to compute F-measure incrementally, we only need to update a_h and c_h as:

$$a_{h+1} = a_h + \bar{\mathbf{y}}_{h+1} \cdot \hat{\mathbf{y}}_{h+1},$$
$$c_{h+1} = c_h + \sum \bar{\mathbf{y}}_{h+1} + \sum \hat{\mathbf{y}}_{h+1}$$

AUROC and AUPRC are different from F-measure in that they need to compute the area value under various thresholds. We introduce two auxiliary hash table L_{+}^{h} and L_{-}^{h} of size m that partition (0,1) into m uniform ranges. For $i \in \{1,\ldots,m\}, L_{+}^{h}[i]$ stores the number of positive examples before (including) h-th iteration with predictions f such that $\sigma(f) \in [(i-1)/m, i/m)$. Similarly, L_{-}^{h} stores negative examples with $\sigma(f) \in [(i-1)/m, i/m)$. σ is the sigmoid function that normalize f to (0,1). Let N_{h}^{+} and N_{h}^{-} denote the number of positive and negative examples respectively. We then compute the True Positive Rate (TPR) and False Positive Rate (FPR) as: $\text{TPR}(i) = \sum_{j=i+1}^{m} L_{+}^{h}[j]/N_{h}^{+}$ and $\text{FPR}(i) = \sum_{j=i+1}^{m} L_{-}^{h}[j]/N_{h}^{-}$. Thus,

$$AUROC = \frac{1}{2} \sum_{i=0}^{m-1} [FPR(i+1) - FPR(i)] [TPR(i) + TPR(i+1)]$$

Similarly, Precision (P) and Recall (R) are computed as: P(i) = $\sum_{j=i+1}^{m} L_{+}^{h}[j] / \sum_{j=i+1}^{m} (L_{h}^{+}[j] + L_{h}^{-}[j])$ and

 $\mathbf{R}(i) = \mathbf{TPR}(i)$. Similarly,

AUPRC =
$$\frac{1}{2} \sum_{i=0}^{m-1} [\mathbf{R}(i) - \mathbf{R}(i+1)] [\mathbf{P}(i) + \mathbf{P}(i+1)].$$

In order to compute AUROC and AUPRC incrementally, we only need to maintain and update L^h_+ and L^h_- .

A.6 **Proof of Proposition 1**

We mainly consider F1-score, whose computation is

$$F(h) = \frac{2(P_1 - \mathtt{fn})}{2P_1 - \mathtt{fn} + \mathtt{fp}},$$

where h can be any hypothesis (classifiers, models, etc.), fn and fp denote the false negative probability and false positive probability, respectively.

Following (Parambath *et al.* 2014), we define the following notations for binary classification:

$$a(heta) = [1 - rac{ heta}{2}, rac{ heta}{2}] \in \mathbb{R}^2,$$

 P_1 : the marginal probability of the positive instances,

 $e = [fn, fp] \in \mathbb{R}^2$: error profile, $E(h) = [fn, fp] \in \mathbb{R}^2$: error profile of h,

$$\boldsymbol{e}(\theta) \in \arg\min_{\boldsymbol{e}' \in \mathcal{E}} \langle \boldsymbol{a}(\theta), \boldsymbol{e}' \rangle.$$

Lemma 1. (Proposition 4 in (Parambath *et al.* 2014)) Let $F^* = \max_{e' \in \mathcal{E}(\mathcal{H})} F(e')$. We have:

$$e \in \arg \min_{e' \in \mathcal{E}(\mathcal{H})} \langle a(F^*), e' \rangle \Leftrightarrow F(e) = F^*.$$

Lemma 2. (In the proof of Proposition 6 in (Parambath *et al.* 2014)) $F(\boldsymbol{e}) = t \Leftrightarrow \langle a(t), \boldsymbol{e} \rangle = \min_{\boldsymbol{e}' \in \mathcal{E}(\mathcal{H})} \langle \boldsymbol{a}(t), \boldsymbol{e}' \rangle = \frac{2P_1(t-1)}{2}$.

Here we re-present Proposition 1 as follows:

Proposition 1. Given the evenly distributed values $\theta_1, ..., \theta_K$ and the cost vector $\mathbf{a}(\theta) = [1 - \frac{\theta}{2}, \frac{\theta}{2}]$, let $\Delta = \frac{\theta_j - \theta_{j+1}}{2} = \frac{1}{2K}$. Denote $F^* = \max_{\mathbf{e}} F(\mathbf{e})$ the maximum F-measure and $F(\mu)$ a function of μ that computes the F-measure achieved by μ . Assume that $\{\mu_h^1, ..., \mu_h^K\}$ minimizes the cost-sensitive loss to a certain degree and $E(\mu) = [\text{fn}, \text{fp}]$, i.e., false negative probability and false positive probability. Then the F-measure achieved by Algorithm 2 has the following lower bound as long as h increases:

$$\max_{j=1,\dots,K} F(\boldsymbol{\mu}_h^j) \ge F^* - \Delta - \frac{\epsilon_0}{P_1},$$

where $k = \arg \max_{j=1,...,K} F(\boldsymbol{\mu}_h^j)$ and $\langle \boldsymbol{a}(\theta_j), \boldsymbol{E}(\boldsymbol{\mu}_h^k) \rangle \leq \min_{\boldsymbol{\mu}} \langle \boldsymbol{a}(\theta_j), \boldsymbol{E}(\boldsymbol{\mu}) \rangle + \epsilon_0.$



Figure S1: Online performance for ratio 1:5

Proof.

$$F^{*} - F(\mu_{h}^{j})$$

$$=F^{*} - \frac{2(P_{1} - E(\mu_{h}^{j}))}{2P_{1} - E_{1}(\mu_{h}^{j}) + E_{2}(\mu_{h}^{j})}$$

$$= \frac{2P_{1}(F^{*} - 1) + \langle a(\theta^{*}), E(\mu_{h}^{j}) \rangle}{2P_{1} - E_{1}(\mu_{h}^{j}) + E_{2}(\mu_{h}^{j})}$$

$$= \frac{\langle a(\theta^{*}) - a(\theta_{j}), E(\mu_{h}^{j}) \rangle + \langle a(\theta_{j}), E(\mu_{h}^{j}) + 2P_{1}(\theta^{*} - 1) \rangle}{2P_{1} - E_{1}(\mu_{h}^{j}) + E_{2}(\mu_{h}^{j})}$$

$$= \frac{(\theta^{*} - \theta_{j}) + \langle a(\theta_{j}), E(\mu_{h}^{j}) \rangle + 2P_{1}(\theta^{*} - 1)}{2P_{1} - E_{1}(\mu_{h}^{j}) + E_{2}(\mu_{h}^{j})}$$

$$\leq \frac{(\theta^{*} - \theta_{j}) + \langle a(\theta_{j}), e(\theta_{j}) \rangle + \epsilon_{0} + 2P_{1}(\theta^{*} - 1)}{2P_{1} - E_{1}(\mu_{h}^{j}) + E_{2}(\mu_{h}^{j})}$$

$$= \theta^{*} - \theta_{j} + \frac{\epsilon_{0}}{2P_{1} - E_{1}(\mu_{h}^{j}) + E_{2}(\mu_{h}^{j})} \qquad (1)$$

A.7 Additional Results

In Figure 1, we only show the online performance with respect to the ratio 1:10. Here we show other imbalance ratios in Figure S1 and Figure S2.

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(c) news20 with ratio 1.17

Figure S2: Online performance for ration 1:20 (1:19)

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